

1. Product Description

Nexto Series is a powerful and complete Programmable Logic Controller (PLC) Series with unique and innovative features. Due to its flexibility, smart design, enhanced diagnostics capabilities and modular architecture, Nexto is suitable for control systems ranging from medium to high-end large applications. Finally, its compact size, high density of points per module and superior performance, allow Nexto Series to be applied in small automation systems with high performance requirements, such as manufacturing applications and industrial machines.

In this context, Nexto Jet is a selection of I/O modules that uses the existing CPUs and modules from Nexto Series to provide the best solution for applications in verticals like infrastructure, building, water, wastewater, food, machines and several OEM projects. Nexto Jet is ideal for systems with no hot-swapping and conformal coating requirements.

Finally, the module NJ1005 is a mixed I/O module that delivers 8 protected source type outputs and 8 isolated sink/source type inputs for general purpose use, and it is a module that uses one rack position.



Its main features are:

- High density, with 16 I/O points in a single width module
- Isolated outputs
- Isolated inputs in two groups
- Short circuit protection and diagnostic for outputs
- Protection against polarity inversion for external power supply
- External power supply low voltage diagnostic
- Display for output/input state indication and diagnostics
- Easy Plug System

ATTENTION

Starting from product revision AB, it was included the connector frontal cover (which was previously exclusive of NX models), thus adding the Easy Plug System feature to this product.

2. Ordering Information

2.1. Included Items

The product package contains the following items:

- NJ1005 module
- 20-terminals connector with wire holder

2.2. Product Code

The following code should be used to purchase the product:

Code	Description
NJ1005	24 Vdc 8 DO Transistor / 8 DI Mixed Module

Table 1: Product Code

3. Related Products

The following product must be purchased separately when necessary:

Code	Description
NX9403	20-terminal connector with cable guides

Table 2: Related Products

4. Innovative Features

Nexto Series brings to the user many innovations regarding utilization, supervision and system maintenance. These features were developed focusing a new concept in industrial automation.



Easy Plug System: Nexto Series has an exclusive method to plug and unplug I/O terminal blocks. The terminal blocks can be easily removed with a single movement and with no special tools. In order to plug the terminal block back to the module, the frontal cover assists the installation procedure, fitting the terminal block to the module.



iF Product Design Award 2012: Nexto Series was the winner of iF Product Design Award 2012 in industry + skilled trades group. This award is recognized internationally as a seal of quality and excellence, considered the Oscars of the design in Europe..

5. Product Features

5.1. General Features

	NJ1005
Backplane rack occupation	1 slot
Number of inputs	8 digital inputs
Number of outputs	8 digital outputs
Update time	2 ms (inputs and outputs)
Input status indication	Yes
Output status indication	Yes
One Touch Diag (OTD)	No
Electronic Tag on Display (ETD)	No
Status and diagnostic indication	Display, web pages and CPU's internal memory
Hot swap capability	No
Wire gauge	0,5 mm ² (20 AWG)
Minimum wire temperature rating	75 °C
Wire material	Copper only
Isolation	
Outputs to inputs	1000 Vac / 1 minute
Outputs to logic	500 Vac / 1 minute
Outputs to protective earth (⊕)	1250 Vac / 1 minute
Inputs group to inputs group	1000 Vac / 1 minute
Inputs to logic	2500 Vac / 1 minute
Inputs to outputs power supply	1000 Vac / 1 minute
Inputs to protective earth (⊕)	2500 Vac / 1 minute
Logic to protective earth (⊕)	1250 Vac / 1 minute
Current consumption from rack PSU	160 mA
Maximum power dissipation	4 W
IP level	IP 20
Operating temperature	0 to 60 °C
Storage temperature	-25 to 75 °C
Operating and storage relative humidity	5% to 96%, non-condensing
Module dimensions (W x H x D)	18.00 x 114.62 x 117.46 mm
Package dimensions (W x H x D)	25.00 x 122.00 x 147.00 mm
Weight	200 g
Weight with package	250 g

Table 3: General Features

Note:

Wire gauge: Crimp terminals for 0.5 mm² wire in each way respecting as described at Nexto Series User Manual - MU214600.

5.2. Standards and Certifications

Standards and Certifications	
IEC	61131-2: Industrial-process measurement and control - Programmable controllers - Part 2: Equipment requirements and tests
CE	2014/30/EU (EMC) 2014/35/EU (LVD) 2011/65/EU and 2015/863/EU (ROHS)
UK CA	S.I. 2016 No. 1091 (EMC) S.I. 2016 No. 1101 (Safety) S.I. 2012 No. 3032 (ROHS)
UL LISTED	UL/cUL Listed – UL 61010-1 UL 61010-2-201 (file E473496)

Table 4: Standards and Certifications

5.3. Transistor Digital Output

	NJ1005
Output type	Transistor isolated source type output
Number of outputs	8
Maximum output current	1 A @ 30 Vdc per output 4 A @ 30 Vdc in group
Leakage current	30 μ A
On state resistance	250 m Ω
External power supply	19.2 to 30 Vdc
Switching time	100 μ s - off-to-on transition 400 μ s - on-to-off transition
Maximum switching frequency	500 Hz
Output update time	2 ms
Configurable parameters	Yes
Output state indication	Yes
Output protections	Yes, power supply polarity inversion protection, protection against surge voltages and short circuit protection

Table 5: Transistor Digital Output Features

Notes:

Maximum output current: When required use a higher current value, it's possible to use more than one output connected on the same load. In this case the maximum current is the sum of individual currents where up to 4 outputs can be used together. For example: It's possible to drive a given load with 1.5 A using 2 outputs. All outputs used on a given load must be enabled/disabled at the same time.

External power supply: The terminals 19 and 20 are used to supply voltage only to the outputs. NJ1005 is supplied by the Power Supply Module placed on the Nexto Backplane Rack.

ATTENTION:

If the external power supply is below the 19.2 V limit, the outputs go to a safe state. However, since the display only shows the outputs' logical state, its indication may not match the physical state of outputs.

Switching time: The required time to turn off one specific output depends on the load. A lower resistance load results in a shorter time to disable the output. The given time refers to the maximum time to disable an output connected to a 12.5 k Ω resistive load, which is the maximum allowable resistance defined by IEC 61131 for digital input modules.

5.4. Digital Input

	NJ1005
Input type	Sink or source type 1
Number of inputs	8
Input voltage	24 Vdc 15 to 30 Vdc for logic level 1 0 to 5 Vdc for logic level 0
Input impedance	4.18 k Ω - input 00 4.90 k Ω - inputs 01 to 07
Maximum input current	6 mA for 24 Vdc – input 00 5 mA for 24 Vdc – inputs 01 to 07
Input state indication	Yes
Input update time	2 ms
Input filter	100 μ s - by hardware 2 ms to 255 ms – by software

Table 6: Digital Input Features

Note:

Input type: NJ1005's inputs are divided in two input groups: 00 to 03 and 04 to 07. Each group can be used as source inputs as well as sink inputs independently of the type used in the other group. To use an input group as source inputs, the respective common terminal must be connected to 24 Vdc. To use an input group as sink inputs, the respective common terminal must be connected to 0 Vdc. For more information please check the section [Installation](#) in this document.

5.5. Compatibility with Other Products

The following table provides information regarding the compatibility of the module NJ1005 and other Nexto Series products.

NJ1005		Compatible Software Version			
Version	Revision	NX3004	NX3005	NX30x0	MasterTool IEC XE
1.2.0.6 or higher	AA	1.6.1.0 or higher	1.6.1.0 or higher	1.6.1.0 or higher	3.02 or higher

Table 7: Compatibility with Other Products

Note:

Revision: If the software is upgraded in the field the product revision indicated on the label will no longer match the actual revision of the product.

ATTENTION

The CPUs and racks of Nexto Series support the use of Nexto Jet Modules. The Nexto Jet is formed by I/Os modules and when used in configuration with CPUs of Nexto Series, no other I/O type of Nexto Series can be used in the same bus.

5.6. Physical Dimensions

Dimensions in mm.

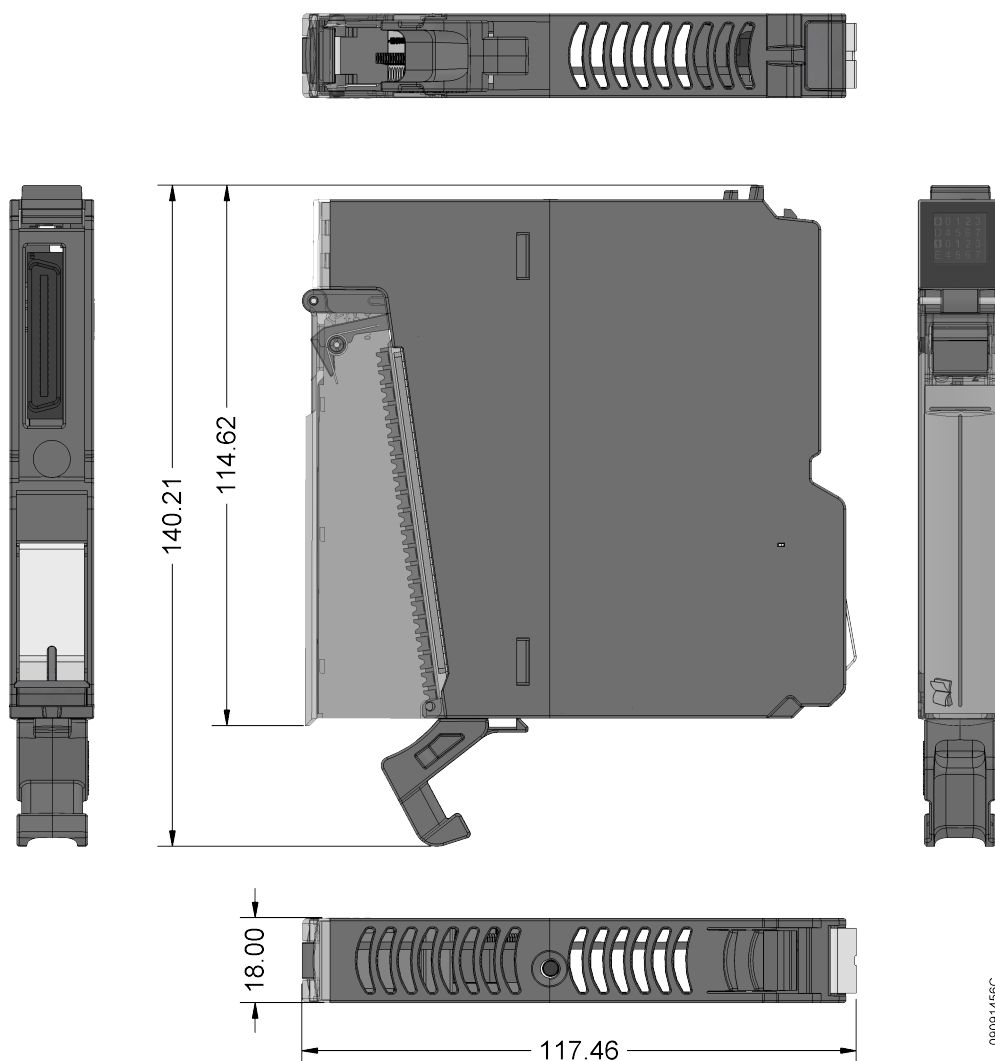


Figure 1: Physical Dimensions

6. Installation

For the correct installation of this product, it is necessary to use a rack (backplane rack) and it must be carried out according to the mechanical and electrical installation instructions that follow.

6.1. Product Identification

This product has some parts that must be observed before installation and use. The following figure identifies each of these parts.

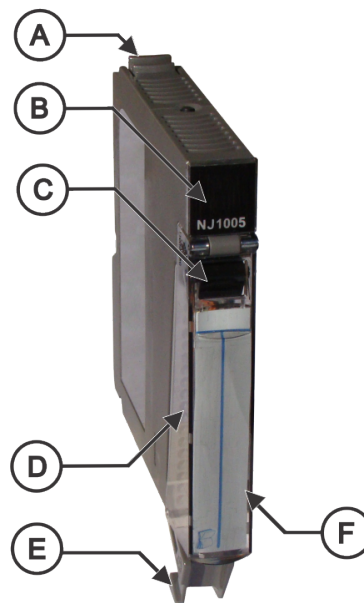


Figure 2: NJ1005

- Ⓐ Fixing lock.
- Ⓑ Status and diagnostic display.
- Ⓒ Terminal block extraction lever.
- Ⓓ Front cover.
- Ⓔ 20 pin terminal block with wire holder.
- Ⓕ Label for module identification.

The product has in its mechanics a label that identifies it and in it are presented some symbols whose meaning is described below:



Attention! Before using the equipment and installing, read the documentation.



Direct Current.

6.2. Electrical Installation

The figure below shows an example where each NJ1005's output is connected to the load and where the inputs 00 to 03 are being used as sink inputs and the inputs 04 to 07 are being used as source inputs.

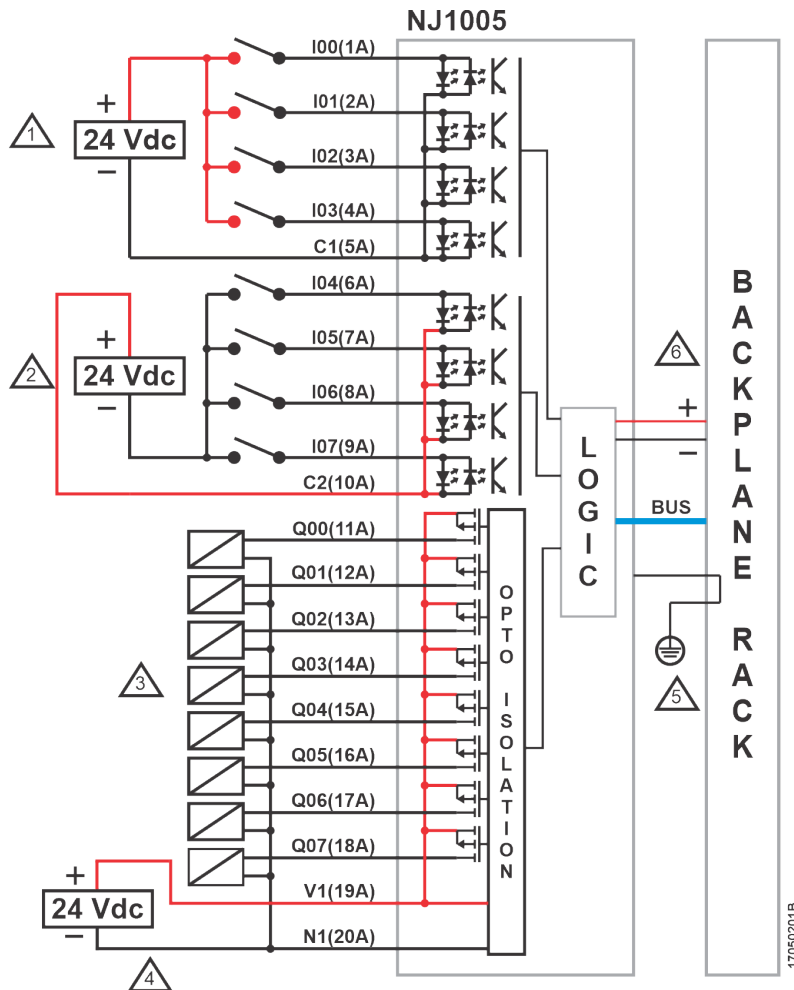


Figure 3: Electrical Installation

Diagram Notes

- ① Typical usage of sink digital inputs. C1 is the 0 Vdc common to input group I00 to I03.
- ② Typical usage of source digital inputs. C2 is the +24 Vdc common to input group I04 to I07.
- ③ Typical usage of source digital outputs.
- ④ External power supply to supply the outputs. V1 is connected to +24 Vdc and N1 is connected to 0 Vdc.
- ⑤ The module is grounded through the Nexto Series backplane racks.
- ⑥ The module power supply is derived from the connection to the backplane rack, not requiring external connections.
- ⊕ Protective conductor terminal.

6.3. Connector Pinout

The following table shows the description of each connector terminal.

Terminal Number	Description
1	Input 00
2	Input 01
3	Input 02
4	Input 03
5	Common for inputs 00 to 03
6	Input 04
7	Input 05
8	Input 06
9	Input 07
10	Common for inputs 04 to 07
11	Output 00
12	Output 01
13	Output 02
14	Output 03
15	Output 04
16	Output 05
17	Output 06
18	Output 07
19	(V1) +24 Vdc for outputs 00 to 07
20	(N1) 0 Vdc for outputs 00 to 07

Table 8: Connector Pinout

6.4. Protection Circuit

For further information, consult the "*Lightning Protection*" section of the Nexto Series User Manual - MU214600.

ATTENTION

Atmospheric discharges (thunders) may cause damages to the product although its protections. Additional protections should be used if the product's power comes from a power supply located outside the panel where it is installed because it could be vulnerable to this kind of discharges. If the field wiring of the output points is susceptible to this kind of discharge, surge suppressors should be used.

6.5. Mechanical and Electrical Assembly

The mechanical and electrical mounting and the connector insertion and removing for a single width I/O modules are described at Nexto Series User Manual – MU214600.

ATTENTION

Products with broken warranty seal are not covered in warranty.

CAUTION



The device is sensitive to static electricity (ESD). Always touch in a metallic grounded object before handling it.

DANGER



Nexto Series can operate with voltage up to 250 Vac. Special care must be taken during the installation, which should only be done by qualified technical personnel. Do not touch on the wiring field when in operation.

7. Configuration

This module was developed to be used with Nexto Series products. All Nexto Series products are configured in MasterTool IEC XE. All configuration data of a given module can be accessed through a double click in it on the Graphical Editor.

7.1. Process Data or I/O Mapping

Process Data, when available, are the variables that are used to access and control the module. The list below describes all variables delivered by NJ1005.

The table below presents the variables organizational structure in the CPU memory.

Besides this data, NJ1005 also provides a set of variables containing information related to diagnostics which are also described in this document.

Variable	Size	Process Data	Description	Type	Update
%QB(n)	BYTE	Digital Outputs - Byte 0	Output Value of channels 10 to 17	Output (Read/Write)	Always
%QB(n+1)	BYTE	High Speed Counter Input 00 Command	Input 00 counter command structure	Output (Write)	Selectable
%QB(n+2)	DWORD	High Speed Counter Input 00 Preset Value	Input 00 counter pre-set command	Output (Write)	Selectable
%QB(n+6)	BYTE	High Speed Counter Input 01 Command	Input 01 counter command structure	Output (Write)	Selectable
%QB(n+7)	DWORD	High Speed Counter Input 01 Preset Value	Input 01 counter pre-set command	Output (Write)	Selectable
%QB(n+11)	BYTE	Pulse-Catch Reset – Byte 0	Reset command to recognize the pulse capture from inputs 00 to 07	Output (Write)	Selectable
%IB(n)	BYTE	Digital Inputs - Byte 0	Input value of channels 00 to 07	Input (Read)	Always
%IB(n+1)	BYTE	High Speed Counter Input 00 Status	Input 00 counter command status	Input (Read)	Selectable

Variable	Size	Process Data	Description	Type	Update
%IB(n+2)	DWORD	High Speed Counter Input 00 Current Value	Input 00 counter value	Input (Read)	Selectable
%IB(n+6)	BYTE	High Speed Counter Input 01 Status	Input 01 counter command status	Input (Read)	Selectable
%IB(n+7)	DWORD	High Speed Counter Input 01 Current Value	Input 01 counter value	Input (Read)	Selectable
%IB(n+11)	DWORD	Input 02 Period	Value of the period measurement of the input 02	Input (Read)	Selectable

Table 9: Process Data

Note:

Update: The field Update indicates if, by default, the respective process data is updated by CPU and NJ1005. When defined as Always, it means that the process data is always updated. When defined as Selectable, it means that the user can select if the respective process data will be updated or not. All these process data are exchanged between CPU and NJ1005 through the bus. To improve CPU performance, it's recommended to update only the process data that will be used in the application.

7.2. Module Parameters

Name	Description	Standard value
Operating Mode	Set special features configuration mode	Mode 0
Input Filter Enable Mask	Enables or disables input filter feature, per channel	FALSE
Input Filter Time Constant	Sets input filter time constant (ms)	7
Pulse-Catch Enable Mask	Enables or disables pulse catch	FALSE
Pulse-Catch Elongation Time	Sets the Elongation Time of the pulse catch (ms)	50
Period Measurement Enable Mask	Enables or disables period measurement (available only to input 02)	FALSE
%Q Start Address of Module Diagnostics Area	Defines the start address of the module diagnostics	-

Table 10: Module Parameters

Notes:

Operating Mode: For further information, the Operating Modes section should be consulted.

Input Filter Enable Mask: The field can be selected by the user to enable the input filter feature in a specific channel. If the input filter is enabled in a channel, the module will reject pulses smaller than the time configured in the Input Filter Time Constant.

Input Filter Time Constant: The field determines the time to apply in the filter and this parameter can be set from 2 to 255 ms. If enabled some different operation mode than Mode 0, this parameter is ignored for inputs related to the selected operating mode, the remaining inputs must have the same behavior of Mode 0.

Pulse-Catch Elongation Time: This field determines the time that the pulse detected by the input module will remain active, so it is suggested that the set value in this field is always greater than the cycle time of application.

7.2.1. Operating Modes

NJ1005 provides five operation modes, where each one has some functionality features in common and also specific features. The table below describes the available features in each operation mode.

Operating Mode	Description
Mode 0	Input 00 to 07: Standard digital input
Mode 1	Input 00 to 07: Pulse catch Input 00 to 07: Standard digital input (only on pulse catch disabled inputs)
Mode 2	Input 00: Counter 1, counting direction defined by software Input 01: Standard digital input Input 02: Period measurement Input 03 to 07: Standard digital input
Mode 3	Input 00: Counter 1, counting direction defined by input 01 Input 01: Counting direction control of Counter 1 Input 02: Period measurement Input 03 to 07: Standard digital input
Mode 4	Input 00: Counter 1, counting direction defined by software Input 01: Counter 2, counting direction defined by software Input 02: Period measurement Input 03 to 07: Standard digital input

Table 11: Operating Mode

7.2.2. Mode 1: Pulse Catch

Pulse catch functionality can be configured when you select the operation mode 1, as can be seen in the table above. This feature is used to detect fast pulses, which can not be identified during a standard scan of the application, and increase them for such a scan can detect.

The capture of the pulse can be enabled individually for each digital input via Pulse-Catch Enable Mask parameter. The inputs that are not used as pulse catch can be used as standard digital input.

The behavior of the pulse catch is associated with the identification of pulses with not less than 1 ms width, generated by field signal in the respective input enabled. When this is identified, the module indicates through the Digital Inputs - Byte 0 variables setting the bit corresponding to input that is with this feature enabled. This bit will remain on for the time configured in the Pulse-Catch Elongation Time parameter. We recommend configuring in this parameter a time greater than the Interval Time of the MainTask; otherwise the standard scan may not detect this.

The command Pulse-Catch Reset has priority over the field signal, i.e., when this command is active for the corresponding input, the pulses generated by the field signal are ignored.

In order to exemplify the behavior described above, the figures below indicate the State of the field signal, Pulse-Catch Reset command and the result of this functionality in Digital Inputs - Byte 0 variables.

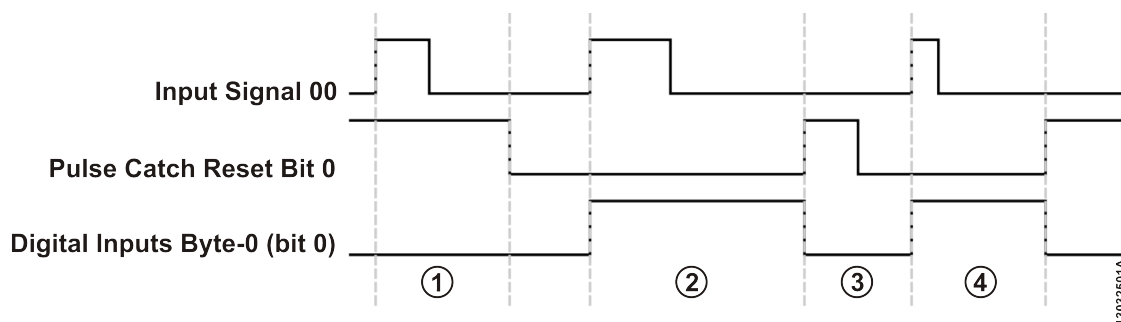


Figure 4: Pulse Catch

Notes:

1. Pulse generated by the field signal more than 1 ms at the input 00 but with the command Pulse-Catch Reset bit 0 on. In this case the user will not identify any change in the Digital Inputs - Byte 0 bit 0 variable.
2. Pulse generated by field signal more than 1 ms at the input 00 with Pulse-Catch Reset bit 0 command off. In this case the module sets the bit 0 of the Digital Inputs - Byte 0 variable, keeping it in TRUE until the reset command. In this case the application scan interval identifies the pulse that was captured by this feature.
3. Displays the reset signal turning off the bit 0 of the Digital Inputs - Byte 0 variable.
4. This case presents a pulse equal to 1 ms in field signal, which is identified by the module. In this way the bit 0 of the Digital Inputs - Byte 0 variable remains on until the reset command.

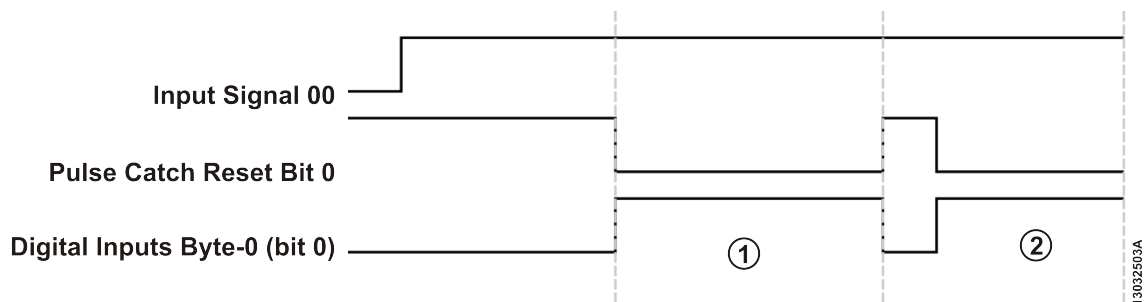


Figure 5: Pulse Catch

Note:

1 and 2: If the field signal does not generate pulses and stay always on, the signal from the Digital Inputs - Byte 0 variable will be switched on whenever there is a transition from the reset command. In this situation, the signal of Digital Inputs - Byte 0 variable may only be turned on when the Pulse-Catch Reset command is off.

7.2.3. Mode 2: Counter

The counter in operation mode 2 is able to register Input 00 count and set the count direction by up and down functions via software command, which is available in bit 0 of the High Speed Counter Input 00 Command, called Direction. The count value can be read through the variable High Speed Counter Input 00 Current Value which can assume the values defined in the count presented on the table of characteristics of the mode 2.

To stop counting, use the Stop Counter command available in the command variable. Other commands like Preset, Reset and Hold counter can also be performed. The logical state of activation of any command is logic level 1, and these will be accepted only if the counter is running or stopped (STOP).

If the Reset and Preset commands are sent simultaneously to the module, the Reset command is performed. The same applies to the Stop and Hold commands, but in this case the Stop command is performed.

The status bit "Direction" – in Run and Stop modes - informs the counting direction. But in Hold mode, it indicates the last valid configuration.

The Reset and Preset status indicate when the command was successfully held. Their value resets when command bit goes to zero.

In case of counter overflow, that is, when the value of the count reaches its maximum value the count will automatically assume the minimum value.

Counter Mode 2	
Count input	Input 00
Count range	-2,147,483,648 to +2,147,483,647
Count direction control	By software
Maximum frequency of the count input (fc)	20 kHz
Minimum time of count direction setting	10 ms
Update time	2 ms
Count input detection edge	Fall, active on logical level 0

Table 12: Counter Mode 2

ATTENTION

It is recommended to use a duty cycle of 50% for counter inputs.

Process Data	Bit	Command	Description
High Speed Counter Input 00 Command	0	Direction	Sets the direction of the count: FALSE – count up TRUE – countdown
	1	Stop Counter	Runs the counter stop FALSE – running counter TRUE – stops the count
	2	Hold Counter	Freezes the count value FALSE – running counter TRUE – freezes value in the variable HSC Input 00 Current Value, but continues to count
	3	Reset Counter	TRUE – returns the count to zero
	4	Preset Counter	TRUE – loads the counter with the value of HSC Input 00 Preset Value
	5..7	Reserved	Reserved
High Speed Counter Input 00 Preset Value	DINT	Contains the value to be loaded into the counter	
High Speed Counter Input 00 Status	0	Direction	Indicates the direction of the count
	1	Stop Counter	Indicates whether the counter is stopped
	2	Hold Counter	Indicates whether the value of the counter was frozen
	3	Reset Counter	Indicates that the count returned to zero
	4	Preset Counter	Indicates that the value of HSC Input 00 Preset Value was loaded into the counter.
	5..7	Reserved	Reserved
High Speed Counter Input 00 Current Value	DINT	Contains the value of the count	

Table 13: Process Data Counter Mode 2

7.2.4. Mode 3: Counter

The count mode available in operating mode 3 has the same functionality of the mode 2 with some particularities: the count direction is not configured by software but rather through the logical state of the input 01. The option “count up” is defined by the logical state 0 and countdown by logical state 1. The other commands have the same operating form of mode 2. The table below presents the general characteristics and limits in this mode.

	Counter Mode 3
Count input	Input 00
Control input	Input 01
Count range	-2,147,483,648 to +2,147,483,647
Maximum frequency of the count input (fc)	20 kHz
Maximum frequency of the control input	2 kHz
Minimum time control input configuration	100 μ s
Update time	2 ms
Count input detection edge	Fall, active on logical level 0
Control input detection edge	Rise – countdown Fall – count up

Table 14: Counter Mode 3

The chart below shows the behavior of the counter input 00 in relation to input 01 which serves to set the count direction.

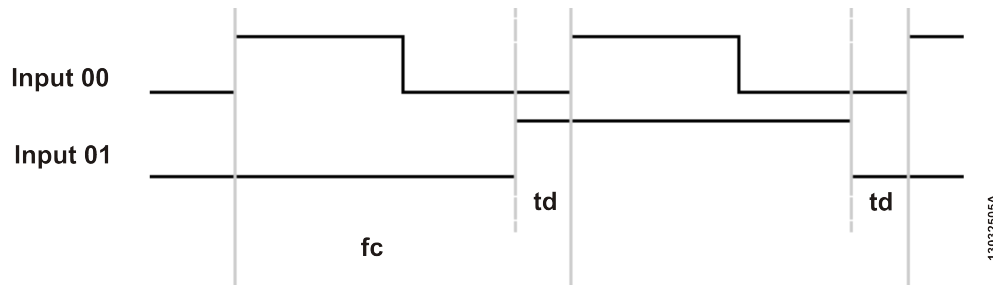


Figure 6: Counter

Notes:

fc: sets the maximum frequency of the count signal.

td: sets the minimum time for count signal identification, and the minimum value is 100 μ s.

7.2.5. Mode 4: Counter

The count mode available in operating mode 4 has two counters: fast count input (Input 00 counter) and count input (Input 01 counter). The commands operate in the same manner as in mode 2, whose count direction is determined by software. The table below presents the general characteristics and limits in this mode.

	Counter Mode 4
Fast count input	Input 00
Count input	Input 01
Count range	-2,147,483,648 to +2,147,483,647
Maximum frequency of the fast count input	20 kHz
Maximum frequency of the count input	2 kHz
Minimum time count direction configuration	10 ms
Update time	2 ms
Fast count input detection edge	Fall, active on logical level 0
Count input detection edge	Fall, active on logical level 0

Table 15: Counter Mode 4

Note:

Update time: Is the time required to update a new measurement.

7.2.6. Period Measurement in Modes 2, 3 and 4

The period measurement mode is available in operating modes 2, 3 and 4, at the input 02. General information and limits are presented in the table below.

	Period Measurement
Measurement input	Input 02
Minimum period / Maximum frequency	200 μ s / 5 kHz
Maximum period / Minimum frequency	1 s / 1 Hz
Sensitivity	1 μ s
Precision	< 2% of the measured value
Pulses for measuring	4 pulses
Update time	2 ms
Detection edge	Fall, active on logical level 0

Table 16: Period Measurement

Notes:

Pulses for measuring: For period measuring are necessary only four pulses on rise edge of the signal.

Update time: Is the time required to update a new measurement.

ATTENTION

If there is no input signal, Input 02 Period will show the last valid value for 2 s and after will show zero, if there is a signal with frequency out of range specified above, the value shown in Input 02 Period is zero.

8. Module Usage

8.1. General Purpose Input Read

NJ1005 has one variable to access its inputs (Digital Inputs - Byte 0). This variable has eight bits where each bit represents the physical state of each input channel. The relation between each bit and its respective input can be found on the Bus I/O Mapping tab.

8.2. General Purpose Output Write





NJ1005 has one variable to control its outputs (Digital Outputs - Byte 0). This variable has eight bits where each bit represents the output state of a given output channel. The relationship between each bit and its respective output can be found on the Bus I/O Mapping tab.

9. Maintenance

Altus recommends that all modules' connections should be checked and any dust or any kind of dirt located in the module's enclosure should be removed at least every 6 months.

This module offers important features to assist users during the maintenance: Status and Diagnostics Indicators, Web Page with Complete Status and Diagnostics List, and Diagnostics Mapped to Variables.

9.1. Status and Diagnostics Indicators

Nexto I/O modules have a display with the following symbols: D, E,  and  and numerical characters. The states of the symbols D, E,  and  are common for all Nexto Series I/O modules. These states can be consulted in the table below.

9.1.1. D and E States

D	E	Description	Cause	Solution	Priority
Off	Off	Display failure or module off	<ul style="list-style-type: none"> - Module disconnected; - External power supply failure; - Hardware failure. 	Check: <ul style="list-style-type: none"> - If the module is completely connected to the rack; - If the rack is powered by an external source; - If the module has external power. 	-
On	Off	Normal use	-	-	9 (Lower)
Blinking 1x	Off	Active diagnostics	There is at least one active diagnostic related to the module.	Check what the active diagnostic is. More information can be found at section Diagnostics Through Variables .	8

D	E	Description	Cause	Solution	Priority
Blinking 2x	Off	No I/O data update	<ul style="list-style-type: none"> - CPU in STOP mode; - Head/Remote in non-ACTIVE state. 	Check: - If the CPU is in operation; - If the Fieldbus Master is in operation; - The integrity of the network between the MODBUS Client and the Head/Remote.	7
Blinking 3x	Off	Reserved	-	-	6
Blinking 4x	Off	Non-fatal fault	Failure in some hardware or software component, which does not have impact on the basic functionality of the product.	Check the module's diagnostic information. If it is a hardware failure, have the part replaced. If it's software, contact Technical Support.	5
Off	Blinking 2x	Loss of bus master	Loss of communication between: - The module and the CPU; - The module and the Head/Remote; - The Head/Remote and the Field Network Master.	Check: - If the module is completely connected to the rack; - If the CPU is in RUN mode; - If the Fieldbus Master is in operation; - Network integrity between PROFIBUS Master and Head/Remote.	4
Off	Blinking 3x	Module without calibration	<ul style="list-style-type: none"> - The module is not calibrated; - There was an error with the calibration value. 	The module must return to the manufacturer.	3
Off	Blinking 1x	Missing or parameterization error	The module isn't parameterized.	Check: - If the module parameterization is correct; - Network integrity between PROFIBUS Master and Head/Remote; - Network integrity between PROFINET Controller and Head/Remote.	2
Off	Blinking 4x	Fatal hardware fault	Hardware fault.	The module must return to the manufacturer.	1 (Higher)

Table 17: Status of Symbols D and E

Notes:

Field net master: There are different field net solutions, using different nomenclatures to refer to the net master. Examples: Profibus Master, MODBUS Client, PROFINET Controller, etc.

Module without calibration: Only valid for modules that have calibration, typically analog modules. Modules that do not have calibration will never show such an indication through the symbols D and E.

9.1.2. 0, 1 and Numerical Characters

The meaning of the numerical characters can be different for specific modules. In case of digital output, the numerical characters show the respective logic output state. When the numerical character is on, the respective output is also on, and if the numerical character is off, the respective output is also off. In case of digital inputs, the numerical characters show the respective logic input state. When the numerical character is on, the respective input is also on, and if the numerical character is off, the respective input is also off. The relationship between the input/output number and its respective numerical character can be found on the following figure.

The segments 0 and 1 are used to group the numerical characters used for the 8 inputs and the numerical characters used for the 8 outputs. The numerical characters that are placed at the right side of character 0 represent the inputs from 00 to 07, where character 0 is related to input 00 and character 7 is related to input 07. In the same way, the numerical characters that are placed at the right side of character 1 represent the outputs from 10 to 17, where character 0 is related to output 10 and character 7 is related to output 17. The figure below shows the relationship between numerical characters and the respective inputs/outputs.

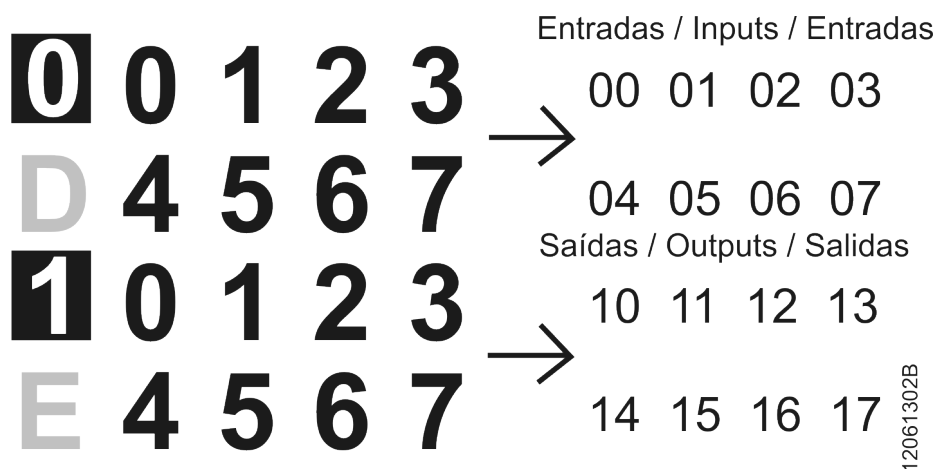


Figure 7: Numerical Character

9.2. Web Page with Complete Status and Diagnostics List

Another way to access diagnostics information on Nexto Series is via web pages. Nexto Series CPU's has an embedded web page server that provides all Nexto status and diagnostics information, which can be accessed using a simple browser.

More information about web page with complete status and diagnostics list can be found at User Manual of each respective CPU (listed at Nexto Series User Manual - MU214600).

9.3. Diagnostics Through Variables

All diagnostics in this module can be accessed through variables that can be handled by the user application or even forwarded to a supervisory system using a communication channel. There are two different ways to access diagnostics in the user application: using symbolic variables with AT directive or addressing memory. Altus recommends use symbolic variables for diagnostic accessing. The table below shows all available diagnostics for this module and their respective memory address, description, symbolic variable and string that will be shown on the CPU graphical display and web.

9.3.1. General Diagnostics

Direct Variable		Diagnostic Message	Symbolic Variable DG_NJ1005.tGeneral.*	Description
Variable	Bit			
%QB(n)	0..7	Reserved		
%QB(n+1)	0	MODULE W/ DIAGNOSTICS	bActiveDiagnostics	TRUE – Module has active diagnostics
		NO DIAG		FALSE – Module doesn't have active diagnostic
	1	MODULE W/ FATAL ERROR	bFatalError	TRUE – Fatal error
		-		FALSE – No fatal error
	2	CONFIG. MISMATCH	bConfigMismatch	TRUE – Parameterization error
		-		FALSE – Parameterization ok
	3	WATCHDOG ERROR	bWatchdogError	TRUE – Watchdog has been detected
		-		FALSE – No watchdog
	4..7	Reserved		

Table 18: General Diagnostics

9.3.2. Detailed Diagnostics

Direct Represent.		Diagnostic Message	Symbolic Variable DG_NJ1005.tDetailed.*	Description
Variable	Bit			
%QB(n+2)	0	OUTPUT SHORT CIRCUIT	bOutputShortCircuit	TRUE – Short circuit at out- puts 10 to 17
		-		FALSE – No short circuit at outputs 10 to 17
	1..7	Reserved		
%QB(n+3)	0	NO EXTERNAL SUPPLY	bNoExternalSupply	TRUE – No external supply at outputs 10 to 17
		-		FALSE – External supply ok at outputs 10 to 17
	1..7	Reserved		

Table 19: Detailed Diagnostics

Notes:

Direct Representation Variable: “n” is the address defined in the field %Q Start Address of Module Diagnostics Area on the NJ1005's configuration screen – Module Parameters tab in the MasterTool IEC XE.

Symbolic Variable: Some symbolic variables serve to access diagnostics. These diagnostics are stored in the direct representation variable, so the AT directive is used to map the symbolic variables in the direct representation variable. The AT directive is a reserved word in the MasterTool IEC XE, that uses this directive to declare the diagnostics automatically on symbolic variables. All symbolic variables declared automatically can be found inside of the Module_Diagnostics object.

10. Manuals

For further technical details, configuration, installation and programming, the table below should be consulted.

The table below is only a guide of some relevant documents that can be useful during the use, maintenance, and programming of this product.

Code	Description	Language
CE114000	Nexto Series – Technical Characteristics	English
CT114000	Série Nexto – Características Técnicas	Portuguese
CS114000	Serie Nexto – Características Técnicas	Spanish
MU214600	Nexto Series User Manual	English
MU214000	Manual de Utilização Série Nexto	Portuguese
MU299609	MasterTool IEC XE User Manual	English
MU299048	Manual de Utilização MasterTool IEC XE	Portuguese
MP399609	MasterTool IEC XE Programming Manual	English
MP399048	Manual de Programação MasterTool IEC XE	Portuguese
MU214608	Nexto PROFIBUS-DP Head Utilization Manual	English
MU214108	Manual de Utilização da Cabeça PROFIBUS-DP Nexto	Portuguese

Table 20: Related Documents