

1. Product Description

Nexto Series is a powerful and complete Programmable Logic Controller (PLC) Series with unique and innovative features. Due to its flexibility, smart design, enhanced diagnostics capabilities and modular architecture, Nexto is suitable for control systems ranging from medium to high-end large applications. Finally, its compact size, high density of points per module and superior performance, allow Nexto Series to be applied in small automation systems with high performance requirements, such as manufacturing applications and industrial machines.

The Series has a wide variety of CPUs, I/O and communication modules with features to fit requirements in different kinds of applications. The options available cover from standard automation systems, high-availability applications where redundancy is a major requirement, distributed applications to functional safety systems.

Nexto Series has a wide range of I/O modules that were designed to fit requirements in different kinds of applications providing high-density points per module. NX1005 is a mixed I/O module that delivers 8 protected source type outputs and 8 isolated sink/source type inputs for general purpose use. NX1005 uses only one slot of Nexto Series Backplane Rack and has exclusive features brought by Nexto Series such as Electronic Tag on Display, Easy Plug System and One Touch Diag.



Its main features are:

- High density, with 16 I/O points in a single width module
- Isolated outputs
- Isolated inputs in two groups
- Short-circuit protection and diagnostic for outputs
- Protection against polarity inversion for external power supply
- External power supply low voltage diagnostic
- Display for output/input state indication and diagnostics
- Easy Plug System
- One Touch Diag
- Electronic Tag on Display

2. Ordering Information

2.1. Included Items

The product package contains the following items:

- NX1005 module
- 20-terminals connector with wire holder

2.2. Product Code

The following code should be used to purchase the product:

| Code | Description |
|--------|--|
| NX1005 | 24 Vdc 8 DO Transistor / 8 DI Mixed Module |

Table 1: Product Code

3. Related Products

The following product must be purchased separately when necessary:

| Code | Description |
|--------|---|
| NX9403 | 20-terminal connector with cable guides |

Table 2: Related Products

4. Innovative Features

Nexto Series brings to the user many innovations regarding utilization, supervision and system maintenance. These features were developed focusing a new concept in industrial automation.



Easy Plug System: Nexto Series has an exclusive method to plug and unplug I/O terminal blocks. The terminal blocks can be easily removed with a single movement and with no special tools. In order to plug the terminal block back to the module, the frontal cover assists the installation procedure, fitting the terminal block to the module.



One Touch Diag: One Touch Diag is an exclusive feature that Nexto Series brings to PLCs. With this new concept, the user can check diagnostic information of any module present in the system directly on CPU's graphic display with one single press in the diagnostic switch of the respective module. OTD is a powerful diagnostic tool that can be used offline (without supervisor or programmer), reducing maintenance and commissioning times.

ETD – Electronic Tag on Display: Another exclusive feature that Nexto Series brings to PLCs is the Electronic Tag on Display. This new functionality brings the process of checking the tag names of any I/O pin or module used in the system directly to the CPU's graphic display. Along with this information, the user can check the description, as well. This feature is extremely useful during maintenance and troubleshooting procedures.



iF Product Design Award 2012: Nexto Series was the winner of iF Product Design Award 2012 in industry + skilled trades group. This award is recognized internationally as a seal of quality and excellence, considered the Oscars of the design in Europe..

5. Product Features

5.1. General Features

| | NX1005 |
|---|--|
| Backplane rack occupation | 1 slot |
| One Touch Diag (OTD) | Yes |
| Electronic Tag on Display (ETD) | Yes |
| Status and diagnostic indication | Display, web pages and CPU's internal memory |
| Hot swap capability | Yes |
| Hardware external interruption | Yes |
| Wire gauge | 0,5 mm ² (20 AWG) |
| Minimum wire temperature rating | 75 °C |
| Wire material | Copper only |
| Isolation | |
| Outputs to inputs | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
| Outputs to logic | 700 Vdc / 1 minute (500 Vac / 1 minute) |
| Outputs to protective earth ⊕ | 2000 Vdc / 1 minute (1250 Vac / 1 minute) |
| Inputs group to inputs group | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
| Inputs to logic | 3500 Vdc / 1 minute (2500 Vac / 1 minute) |
| Inputs to outputs power supply | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
| Inputs to protective earth ⊕ | 3500 Vdc / 1 minute (2500 Vac / 1 minute) |
| Logic to protective earth ⊕ | 2000 Vdc / 1 minute (1250 Vac / 1 minute) |
| Current consumption from rack PSU | 160 mA |
| Maximum power dissipation | 4 W |
| IP level | IP 20 |
| Operating temperature | 0 to 60 °C |
| Storage temperature | -25 to 75 °C |
| Operating and storage relative humidity | 5% to 96%, non-condensing |
| Conformal coating | Yes |
| Module dimensions (W x H x D) | 18.00 x 114.62 x 117.46 mm |
| Package dimensions (W x H x D) | 25.00 x 122.00 x 147.00 mm |
| Weight | 200 g |
| Weight with package | 250 g |

Table 3: General Features

Note:

Conformal coating: Conformal coating protects the electronic components inside the product from moisture, dust and other harsh elements to electronic circuits.

Wire gauge: Crimp terminals for 0.5 mm² wire in each way respecting as described at Nexto Series User Manual - MU214600.

5.2. Standards and Certifications



| Standards and Certifications | |
|---|---|
| IEC | 61131-2: Industrial-process measurement and control - Programmable controllers - Part 2: Equipment requirements and tests |
|  | DNV Type Approval – DNV-CG-0339 (TAA000013D) |
| CE | 2014/30/EU (EMC) 2014/35/EU (LVD) 2011/65/EU and 2015/863/EU (ROHS) |
| UK CA | S.I. 2016 No. 1091 (EMC) S.I. 2016 No. 1101 (Safety) S.I. 2012 No. 3032 (ROHS) |
|  | UL/cUL Listed – UL 61010-1 UL 61010-2-201 (file E473496) |
| EAC | TR 004/2011 (LVD) CU TR 020/2011 (EMC) |

Table 4: Standards and Certifications

5.3. Transistor Digital Output

| | NX1005 |
|-----------------------------|---|
| Output type | Transistor isolated source type output |
| Number of outputs | 8 |
| Maximum output current | 1 A @ 30 Vdc per output 4 A @ 30 Vdc in group |
| Leakage current | 30 μ A |
| On state resistance | 250 m Ω |
| External power supply | 19.2 to 30 Vdc |
| Switching time | 100 μ s - off-to-on transition 400 μ s - on-to-off transition |
| Maximum switching frequency | 500 Hz |
| Output update time | 2 ms |
| Output state indication | Yes |
| Output protections | Yes, power supply polarity inversion protection, protection against surge voltages and short circuit protection |

Table 5: Transistor Digital Output Features

Notes:

Maximum output current: When required use a higher current value, it's possible to use more than one output connected on the same load. In this case the maximum current is the sum of individual currents where up to 4 outputs can be used together. For example: It's possible to drive a given load with 1.5 A using 2 outputs. All outputs used on a given load must be enabled/disabled at the same time.

External power supply: The terminals 19 and 20 are used to supply voltage only to the outputs. NX1005 is supplied by the Power Supply Module placed on the Nexto Backplane Rack.

ATTENTION

If the external power supply is below the 19.2 V limit, the outputs go to a safe state. However, since the display only shows the outputs' logical state, its indication may not match the physical state of outputs.

Switching time: The required time to turn off one specific output depends on the load. A lower resistance load results in a shorter time to disable the output. The given time refers to the maximum time to disable an output connected to a 12.5 k Ω resistive load, which is the maximum allowable resistance defined by IEC 61131 for digital output modules.

5.4. Digital Input

| NX1005 | |
|------------------------|--|
| Input type | Sink or source type 1 |
| Number of inputs | 8 |
| Input voltage | 24 Vdc 15 to 30 Vdc for level logic 1 0 to 5 Vdc for level logic 0 |
| Input impedance | 4.18 k Ω - input 00 4.90 k Ω - inputs 01 to 07 |
| Maximum input current | 6 mA for 24 Vdc – input 00 5 mA for 24 Vdc – input 01 to 07 |
| Input state indication | Yes |
| Input update time | 2 ms |
| Input filter | 100 μ s - by hardware 2 ms to 255 ms – by software |

Table 6: Digital Input Features

Note:

Input type: NX1005's inputs are divided in two input groups: 00 to 03 and 04 to 07. Each group can be used as source inputs as well as sink inputs independently of the type used in the other group. To use an input group as source inputs, the respective common terminal must be connected to 24 Vdc. To use an input group as sink inputs, the respective common terminal must be connected to 0 Vdc. For more information please check the section [Installation](#) in this document.

5.5. Compatibility with Other Products

The following table provides information regarding the compatibility of the module NX1005 and Nexto Series programming tool MasterTool IEC XE.

| NX1005 | | | Software Version Compatible | |
|-------------------|--------------|-------------------------|-----------------------------|-------------------|
| Version | Revision | Feature | MasterTool IEC XE | Nexto CPU's |
| 1.0.0.0 | AA | Mode 0 | 1.22 or higher | 1.0.0.9 or higher |
| 1.1.0.1 or higher | AB or higher | Mode 1, 2, 3, 4 | 1.29 or higher | 1.0.0.9 or higher |
| 1.1.0.1 or higher | AB or higher | Hardware External Event | 1.31 or higher | 1.2.2.1 or higher |

Table 7: Compatibility with Other Products

Notes:

Mode 1, 2, 3, 4: The pulse capture, counters and period measurement features are only available from the software versions indicated in the table.

Hardware external event: The hardware external event feature is available from the software versions indicated in the table. For a digital input to be used in events detection it should be a standard input. So, it should not have counters or other features linked to it. More information about Hardware External Event can be found at User Manual of each respective CPU (listed at manual of Nexto Series - MU214600).

Product review: If the software is upgraded in the field the product reviewing indicated on the label will no longer match the actual review of the product.

5.6. Physical Dimensions

Dimensions in mm.

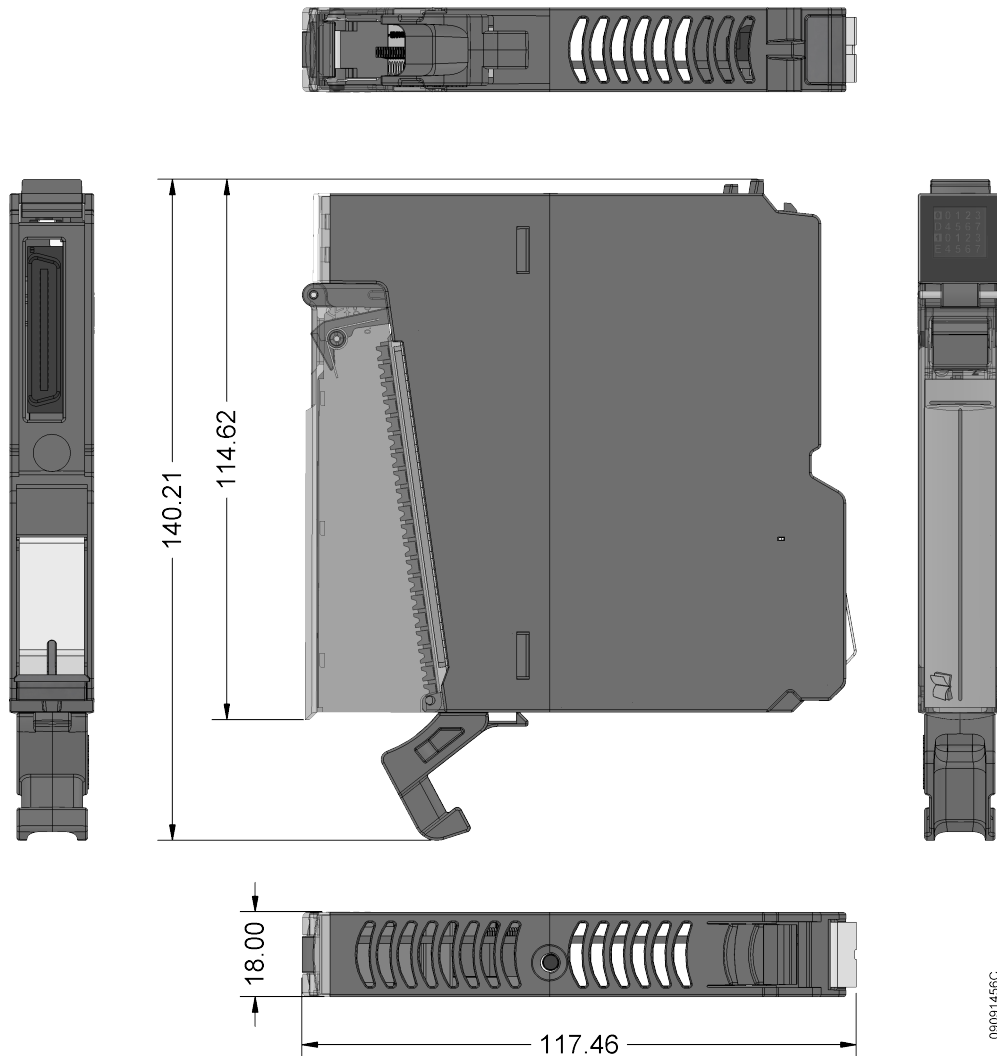


Figure 1: Physical Dimensions

6. Installation

For the correct installation of this product, it is necessary to use a rack (backplane rack) and it must be carried out according to the mechanical and electrical installation instructions that follow.

6.1. Product Identification

This product has some parts that must be observed before installation and use. The following figure identifies each of these parts.

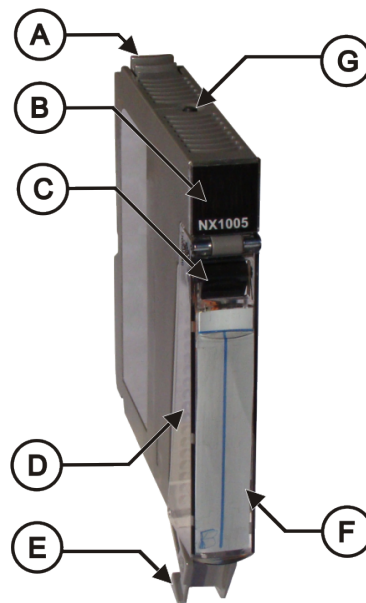


Figure 2: NX1005

- Ⓐ Fixing lock.
- Ⓑ Status and diagnostic display.
- Ⓒ Terminal block extraction lever.
- Ⓓ Front cover.
- Ⓔ 20 pin terminal block with wire holder.
- Ⓕ Label for module identification.
- Ⓖ Diagnostic switch.

The product has in its mechanics a label that identifies it and in it are presented some symbols whose meaning is described below:



Attention! Before using the equipment and installing, read the documentation.



Direct Current.

6.2. Electrical Installation

The figure below shows an example where each NX1005's output is connected to the load and where the inputs 00 to 03 are being used as sink inputs and the inputs 04 to 07 are being used as source inputs.

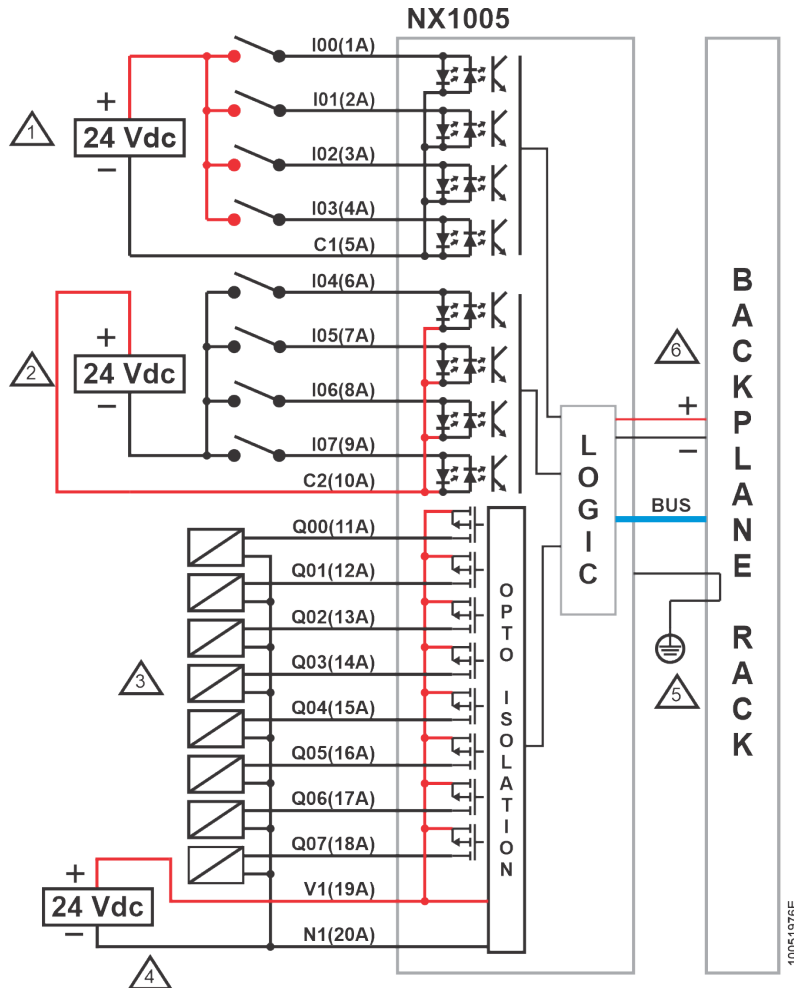


Figure 3: Electrical Installation

Diagram Notes

- ① Typical usage of sink digital inputs, C1 is the 0 Vdc common to input group I00 to I03.
- ② Typical usage of source digital inputs, C2 is the +24 Vdc common to input group I04 to I07.
- ③ Typical usage of source digital outputs.
- ④ External power supply to supply the outputs, V1 is connected to +24 Vdc and N1 is connected to 0 Vdc.
- ⑤ The module is grounded through the Nexto Series backplane racks.
- ⑥ The module power supply is derived from the connection to the backplane rack, not requiring external connections.
- ⊕ Protective conductor terminal.

6.3. Connector Pinout

The following table shows the description of each connector terminal.

| Terminal Number | Description |
|-----------------|------------------------------------|
| 1 | Input 00 |
| 2 | Input 01 |
| 3 | Input 02 |
| 4 | Input 03 |
| 5 | Common for inputs 00 to 03 |
| 6 | Input 04 |
| 7 | Input 05 |
| 8 | Input 06 |
| 9 | Input 07 |
| 10 | Common for inputs 04 to 07 |
| 11 | Output 00 |
| 12 | Output 01 |
| 13 | Output 02 |
| 14 | Output 03 |
| 15 | Output 04 |
| 16 | Output 05 |
| 17 | Output 06 |
| 18 | Output 07 |
| 19 | (V1) + 24 Vdc for outputs 00 to 07 |
| 20 | (N1) 0 Vdc for outputs 00 to 07 |

Table 8: Connector Pinout

6.4. Protection Circuit

For further information, consult the "*Lightning Protection*" section of the Nexto Series User Manual - MU214600.

ATTENTION

Atmospheric discharges (thunders) may cause damages to the product although its protections. Additional protections should be used if the product's power comes from a power supply located outside the panel where it is installed because it could be vulnerable to this kind of discharges. If the field wiring of the output points is susceptible to this kind of discharge, surge suppressors should be used.

6.5. Mechanical and Electrical Assembly

The mechanical and electrical mounting and the connector insertion and removing for a single width I/O modules are described at Nexto Series User Manual – MU214600.

ATTENTION

Products with broken warranty seal are not covered in warranty.

CAUTION



The device is sensitive to static electricity (ESD). Always touch in a metallic grounded object before handling it.

DANGER



Nexto Series can operate with voltage up to 250 Vac. Special care must be taken during the installation, which should only be done by qualified technical personnel. Do not touch on the wiring field when in operation.

7. Configuration

This module was developed to be used with Nexto Series products. All Nexto Series products are configured in MasterTool IEC XE. All configuration data of a given module can be accessed through a double click in it on the Graphical Editor.

7.1. Process Data or I/O Mapping in PROFIBUS-DP Network

Process Data, when available, are the variables that are used to access and control the module. The list below describes all variables delivered by NX1005.

The process data of the module, when inserted in a PROFIBUS network, can be accessed through variables. The NX1005 module has a byte to access the input data and another byte to access the output data. The module NX1005 HSC is described in the table below that presents the variables organizational structure in the UCP memory.

Besides this data, NX1005 also provides a set of variables containing information related to diagnostics which are also described in this document.

| Variable | Size | Process Data | Description | Type | Update |
|-----------|-------|--|---|---------------------|------------|
| %QB(n) | BYTE | Digital Outputs - Byte 0 | Output Value of channels 10 to 17 | Output (Read/Write) | Always |
| %QB(n+1) | BYTE | High Speed Counter Input 00 Command | Input 00 counter command structure | Output (Write) | Selectable |
| %QB(n+2) | DWORD | High Speed Counter Input 00 Preset Value | Input 00 counter pre-set command | Output (Write) | Selectable |
| %QB(n+6) | BYTE | High Speed Counter Input 01 Command | Input 01 counter command structure | Output (Write) | Selectable |
| %QB(n+7) | DWORD | High Speed Counter Input 01 Preset Value | Input 01 counter pre-set command | Output (Write) | Selectable |
| %QB(n+11) | BYTE | Pulse-Catch Reset – Byte 0 | Reset command to recognize the pulse capture from inputs 00 to 07 | Output (Write) | Selectable |
| %IB(n) | BYTE | Digital Inputs - Byte 0 | Input value of channel 00-07 | Input (Read) | Always |

| Variable | Size | Process Data | Description | Type | Update |
|-----------|-------|---|---|--------------|------------|
| %IB(n+1) | BYTE | High Speed Counter Input 00 Status | Input 00 counter command status | Input (Read) | Selectable |
| %IB(n+2) | DWORD | High Speed Counter Input 00 Current Value | Input 00 counter value | Input (Read) | Selectable |
| %IB(n+6) | BYTE | High Speed Counter Input 01 Status | Input 01 counter command status | Input (Read) | Selectable |
| %IB(n+7) | DWORD | High Speed Counter Input 01 Current Value | Input 01 counter value | Input (Read) | Selectable |
| %IB(n+11) | DWORD | Input 02 Period | Value of the period measurement of the input 02 | Input (Read) | Selectable |

Table 9: Process Data

Note:

Update: The field Update indicates if, by default, the respective process data is updated by CPU and NX1005. When defined as Always, it means that the process data is always updated. When defined as Selectable, means that the user can select if the respective process data will be updated or not. All these process data are exchanged between CPU and NX1005 through the bus. To improve CPU performance, it's recommended to update only the process data that will be used in the application.

7.2. Module Parameters

| Name | Description | Standard value |
|---|---|----------------|
| Operating Mode | Set special features configuration mode | Mode 0 |
| Input Filter Enable Mask | Enables or disables input filter feature, per channel | False |
| Input Filter Time Constant | Sets input filter time constant (ms) | 7 |
| Pulse-Catch Enable Mask | Enables or disables pulse catch | False |
| Pulse-Catch Elongation Time | Sets the Elongation Time of the pulse catch (ms) | 50 |
| Period Measurement Enable Mask | Enables or disables period measurement (available only to input 02) | False |
| %Q Start Address of Module Diagnostics Area | Defines the start address of the module diagnostics | - |

Table 10: Module Parameters

Notes:

Operating Mode: For further information, the Operating Modes section should be consulted.

Input Filter Enable Mask: The field can be selected by the user to enable the input filter feature in a specific channel. If the input filter is enabled in a channel, the module will reject pulses smaller than the time configured in the Input Filter Time Constant.

Input Filter Time Constant: The field determines the time to apply in the filter and this parameter can be set from 2 to 255 ms. If enabled some different operation mode than Mode 0, this parameter is ignored for inputs related to the selected operating mode, the remaining inputs must have the same behavior of Mode 0.

Elongation Time of Pulse Catch: This field determines the time that the pulse detected by the input module will remain active, so it is suggested that the set value in this field is always greater than the cycle time of application.

7.2.1. Operating Modes

NX1005 provides five operation modes, where each one has some functionality features in common and also specific features. The table below describes the available features in each operation mode.

| Operating Mode | Description |
|----------------|--|
| Mode 0 | Input 00 to 07: Standard digital input |
| Mode 1 | Input 00 to 07: Pulse catch Input 00 to 07: Standard digital input (only on pulse catch disabled inputs) |
| Mode 2 | Input 00: Counter 1, counting direction defined by software Input 01: Standard digital input Input 02: Period measurement Input 03 to 07: Standard digital input |
| Mode 3 | Input 00: Counter 1, counting direction defined by input 01 Input 01: counting direction control of Counter 1 Input 02: Period measurement Input 03 to 07: Standard digital input |
| Mode 4 | Input 00: Counter 1, counting direction defined by software Input 01: Counter 2, counting direction defined by software Input 02: Period measurement Input 03 to 07: Standard digital input |

Table 11: Operating Mode

7.2.2. Mode 1: Pulse Catch

Pulse catch functionality can be configured when you select the operation mode 1, as can be seen in the table above. This feature is used to detect fast pulses, which can not be identified during a standard scan of the application, and increase them for such a scan can detect.

The capture of the pulse can be enabled individually for each digital input via Pulse-Catch Enable Mask parameter. The inputs that are not used as pulse catch can be used as standard digital input.

The behavior of the pulse catch is associated with the identification of pulses with not less than 1 ms width, generated by field signal in the respective input enabled. When this is identified, the module indicates through the Digital Inputs Byte-0 variables setting the bit corresponding to input that is with this feature enabled. This bit will remain on for the time configured in the Pulse-Catch Elongation Time parameter. We recommend configuring in this parameter a time greater than the Interval Time of the Main Task; otherwise the standard scan may not detect this.

The command Pulse-Catch Reset has priority over the field signal, i.e., when this command is active for the corresponding input, the pulses generated by the field signal are ignored.

In order to exemplify the behavior described above, the figures below indicate the State of the field signal, Pulse-Catch Reset command and the result of this functionality in Digital Inputs Byte-0 variables.

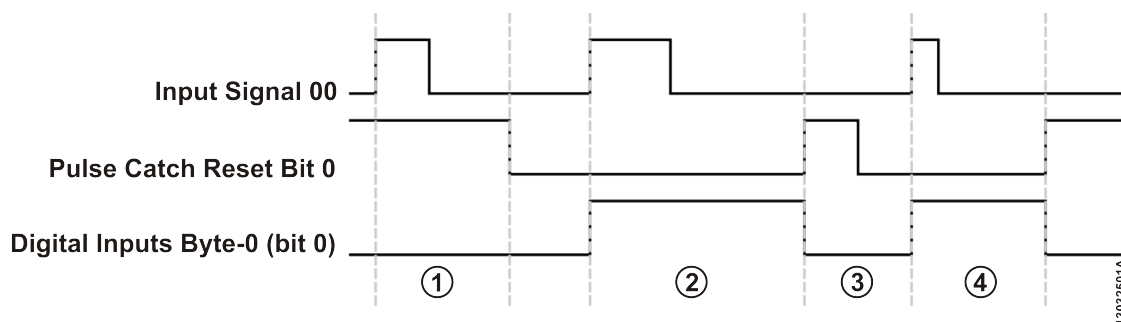


Figure 4: Pulse Catch

Notes:

1. Pulse generated by the field signal more than 1 ms at the input 00 but with the command Pulse-Catch Reset bit 0 on, in this case the user will not identify any change in the Digital Inputs Byte-0 bit 0 variable.
2. Pulse generated by field signal more than 1 ms at the input 00 with Pulse-Catch Reset bit 0 command off; in this case the module sets the bit 0 of the Digital Inputs Byte-0 variable, keeping it in TRUE until the reset command. In this case the application scan interval identifies the pulse that was captured by this feature.
3. Displays the reset signal turning off the bit 0 of the Digital Inputs Byte-0 variable.
4. This case presents a pulse equal to 1 ms in field signal, which is identified by the module. In this way the bit 0 of the Digital Inputs Byte-0 variable remains on until the reset command.

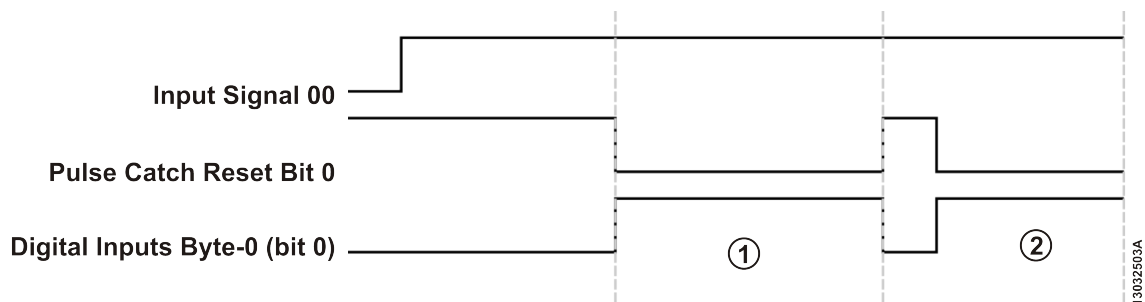


Figure 5: Pulse Catch

Note:

1 and 2: If the field signal does not generate pulses and stay always on, the signal from the Digital Inputs Byte-0 variable will be switched on whenever there is a transition from the reset command. In this situation, the signal of Digital Inputs Byte-0 variable may only be turned on when the Pulse-Catch Reset command is off.

7.2.3. Mode 2: Counter

The counter in operation mode 2 is able to register Input 00 count and set the count direction by up and down functions via software command, which is available in bit 0 of the High Speed Counter Input 00 Command, called Direction. The count value can be read through the variable High Speed Counter Input 00 Current Value which can assume the values defined in the count presented on the table of characteristics of the mode 2.

To stop counting, use the Stop Counter command available in the command variable. Other commands like Preset, Reset and Hold counter can also be performed. The logical state of activation of any command is logic level 1, and these will be accepted only if the counter is running or stopped (STOP).

If the Reset and Preset commands are sent simultaneously to the module, the Reset command is performed. The same applies to the Stop and Hold commands, but in this case the Stop command is performed.

The status bit "Direction" – in Run and Stop modes - informs the counting direction. But in Hold mode, it indicates the last valid configuration.

The Reset and Preset status indicate when the command was successfully held. Their value resets when command bit goes to zero.

In case of counter overflow, that is, when the value of the count reaches its maximum value the count will automatically assume the minimum value.

| Counter Mode 2 | |
|---|----------------------------------|
| Count input | Input 00 |
| Count range | -2,147,483,648 to +2,147,483,647 |
| Count direction control | By software |
| Maximum frequency of the count input (fc) | 20 kHz |
| Minimum time of count direction setting | 10 ms |
| Update time | 2 ms |
| Count input detection edge | Fall, active on logical level 0 |

Table 12: Counter Mode 2

ATTENTION

It is recommended to use a duty-cycle of 50% for counter inputs.

| Process Data | Bit | Command | Description |
|--|------|--|---|
| High Speed Counter Input 00 Command | 0 | Direction | Sets the direction of the count: FALSE – count up TRUE – countdown |
| | 1 | Stop Counter | Runs the counter stop FALSE – running counter TRUE – stops the count |
| | 2 | Hold Counter | Freezes the count value FALSE – running counter TRUE – freezes value in the variable HSC Input 00 Current Value, but continues to count |
| | 3 | Reset Counter | TRUE – returns the count to zero |
| | 4 | Preset Counter | TRUE – loads the counter with the value of HSC Input Preset Value |
| | 5..7 | Reserved | Reserved |
| High Speed Counter Input 00 Preset Value | DINT | Contains the value to be loaded into the counter | |
| High Speed Counter Input 00 Status | 0 | Direction | Indicates the direction of the count |
| | 1 | Stop Counter | Indicates whether the counter is stopped |
| | 2 | Hold Counter | Indicates whether the value of the counter was frozen |
| | 3 | Reset Counter | Indicates that the count returned to zero |
| | 4 | Preset Counter | Indicates that the value of HSC Input Preset Value was loaded into the counter. |
| | 5..7 | Reserved | Reserved |
| High Speed Counter Input 00 Current Value | DINT | Contains the value of the count | |

Table 13: Process Data Counter Mode 2

7.2.4. Mode 3: Counter

The count mode available in operating mode 3 has the same functionality of the mode 2 with some particularities: the count direction is not configured by software but rather through the logical state of the input 01. The option “count up” is defined by the logical state 0 and countdown by logical state 1. The other commands have the same operating form of mode 2. The table below presents the general characteristics and limits in this mode.

| | Counter Mode 3 |
|---|-------------------------------------|
| Count input | Input 00 |
| Control input | Input 01 |
| Count range | -2,147,483,648 to +2,147,483,647 |
| Maximum frequency of the count input (fc) | 20 kHz |
| Maximum frequency of the control input | 2 kHz |
| Minimum time control input configuration | 100 μ s |
| Update time | 2 ms |
| Count input detection edge | Fall, active on logical level 0 |
| Control input detection edge | Rise – countdown Fall – count up |

Table 14: Counter Mode 3

The chart below shows the behavior of the counter input 00 in relation to input 01 which serves to set the count direction.

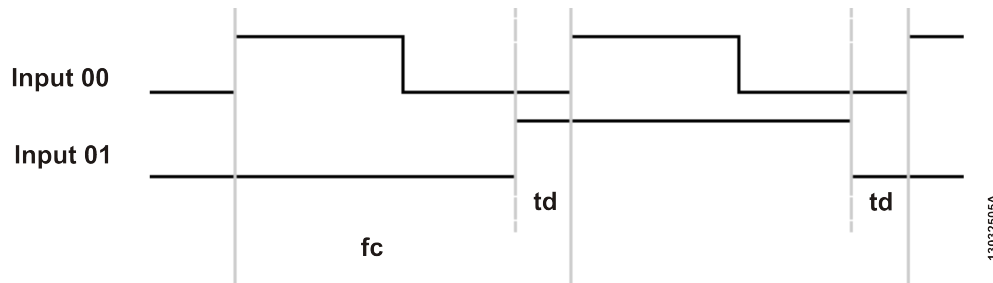


Figure 6: Counter

Notes:

fc: sets the maximum frequency of the count signal.

td: sets the minimum time for count signal identification, and the minimum value is 100 μ s.

7.2.5. Mode 4: Counter

The count mode available in operating mode 4 has two counters: fast count input (Input 00 counter) and count input (Input 01 counter). The commands operate in the same manner as in mode 2, whose count direction is determined by software. The table below presents the general characteristics and limits in this mode.

| | Counter Mode 4 |
|--|----------------------------------|
| Fast count input | Input 00 |
| Count input | Input 01 |
| Count range | -2,147,483,648 to +2,147,483,647 |
| Maximum frequency of the fast count input | 20 kHz |
| Maximum frequency of the count input | 2 kHz |
| Minimum time count direction configuration | 10 ms |
| Update time | 2 ms |
| Fast count input detection edge | Fall, active on logical level 0 |
| Count input detection edge | Fall, active on logical level 0 |

Table 15: Counter Mode 4

Note:

Update time: Is the time required to update a new measurement.

7.2.6. Period Measurement in Modes 2, 3 and 4

The period measurement mode is available in operating modes 2, 3 and 4, at the input 02. General information and limits are presented in the table below.

| | Period Measurement |
|------------------------------------|---------------------------------|
| Measurement input | Input 02 |
| Minimum period / Maximum frequency | 200 μ s / 5 kHz |
| Maximum period / Minimum frequency | 1 s / 1 Hz |
| Sensitivity | 1 μ s |
| Precision | < 2% of the measured value |
| Pulses for measuring | 4 pulses |
| Update time | 2 ms |
| Detection edge | Fall, active on logical level 0 |

Table 16: Period Measurement

Notes:

Pulses for measuring: For period measuring are necessary only four pulses on rise edge of the signal.

Update time: Is the time required to update a new measurement.

ATTENTION

If there is no input signal, Input 02 Period will show the last valid value for 2s and after will show zero, if there is a signal with frequency out of range specified above, the value shown in Input 02 Period is zero.

8. Module Usage

8.1. General Purpose Input Read

NX1005 has one variable to access its inputs (Digital Inputs Byte-0). This variable has eight bits where each bit represents the physical state of each input channel. The relation between each bit and its respective input can be found on the Bus I/O Mapping tab.

8.2. General Purpose Output Write

NX1005 has one variable to control its outputs (Digital Outputs Byte-0). This variable has eight bits where each bit represents the output state of a given output channel. The relationship between each bit and its respective output can be found on the Bus I/O Mapping tab.

9. Maintenance

Altus recommends that all modules' connections should be checked and any dust or any kind of dirt in the module's enclosure should be removed at least every 6 months.

This module offers five important features to assist users during maintenance: Electronic Tag on Display, One Touch Diag, status and diagnostics indicators, web page with complete status and diagnostics list, and diagnostics mapped to internal memory.





9.1. Electronic Tag on Display and One Touch Diag

Electronic Tag on Display and One Touch Diag are important features that provide to the user the option to check the tag, description and diagnostics related to a given module directly on the CPU display.

Electronic Tag on Display and One Touch Diag are easy-to-use features. To check the tag and diagnostics of a given module, it's required only one short press (shorter than 1 s) on its diagnostic switch. After pressing once, CPU will start to scroll tag information and diagnostic information of the module. To access the respective module description just long press (longer than 1 s) the diagnostics switch of the respective module.

More information about Electronic Tag on Display and One Touch Diag can be found at User Manual of each respective CPU (listed at manual of Nexto Series - MU214600).

9.2. Status and Diagnostics Indicators

Nexto I/O modules have a display with the following symbols: D, E,  and  and numerical characters. The states of the symbols D, E,  and  are common for all Nexto Series I/O modules. These states can be consulted in the table below.

9.2.1. D and E States

| D | E | Description | Cause | Solution | Priority |
|-----|-----|-------------------------------|---|---|----------|
| Off | Off | Display failure or module off | <ul style="list-style-type: none"> - Module disconnected; - External power supply failure; - Hardware failure. | Check: <ul style="list-style-type: none"> - If the module is completely connected to the rack; - If the rack is powered by an external source; - If the module has external power. | - |

| D | E | Description | Cause | Solution | Priority |
|-------------|-------------|-----------------------------------|--|---|------------|
| On | Off | Normal use | - | - | 9 (Lower) |
| Blinking 1x | Off | Active diagnostics | There is at least one active diagnostic related to the module. | Check what the active diagnostic is. More information can be found at section Diagnostics Through Variables . | 8 |
| Blinking 2x | Off | No I/O data update | <ul style="list-style-type: none"> - CPU in STOP mode; - Head/Remote in non-ACTIVE state. | Check: - If the CPU is in operation; - If the Fieldbus Master is in operation; - The integrity of the network between the MODBUS Client and the Head/Remote. | 7 |
| Blinking 3x | Off | Reserved | - | - | 6 |
| Blinking 4x | Off | Non-fatal fault | Failure in some hardware or software component, which does not have impact on the basic functionality of the product. | Check the module's diagnostic information. If it is a hardware failure, have the part replaced. If it's software, contact Technical Support. | 5 |
| Off | Blinking 2x | Loss of bus master | Loss of communication between: <ul style="list-style-type: none"> - The module and the CPU; - The module and the Head/Remote; - The Head/Remote and the Field Network Master. | Check: - If the module is completely connected to the rack; - If the CPU is in RUN mode; - If the Fieldbus Master is in operation; - A integridade da rede entre o Mestre Profibus e a Cabeça/Remota. | 4 |
| Off | Blinking 3x | Module without calibration | <ul style="list-style-type: none"> - The module is not calibrated; - There was an error with the calibration value. | The module must return to the manufacturer. | 3 |
| Off | Blinking 1x | Missing or parameterization error | The module isn't parameterized. | Check: - If the module parameterization is correct; - A integridade da rede entre o Mestre Profibus e a Cabeça/Remota; - Network integrity between PROFINET Controller and Head/Remote. | 2 |
| Off | Blinking 4x | Fatal hardware fault | Hardware fault. | The module must return to the manufacturer. | 1 (Higher) |

Table 17: Status of Symbols D and E

Notes:

Field net master: There are different field net solutions, using different nomenclatures to refer to the net master. Examples: Profibus Master, MODBUS Client, PROFINET Controller, etc.

Module without calibration: Only valid for modules that have calibration, typically analog modules. Modules that do not have calibration will never show such an indication through the symbols D and E.

9.2.2. 0, 1 and Numerical Characters

The segments 0 and 1 are used to group the numerical characters used for the 8 inputs and the numerical characters used for the 8 outputs. The numerical characters that are placed at the right side of character 0 represent the inputs from 00 to 07, where character 0 is related to input 00 and character 7 is related to input 07. In the same way, the numerical characters that are placed at the right side of character 1 represent the outputs from 10 to 17, where character 0 is related to output 10 and character 7 is related to output 17. The figure below shows the relationship between numerical characters and the respective inputs/outputs.

The meaning of the numerical characters can be different for specific modules. In case of digital output, the numerical characters show the respective logic output state. When the numerical character is on, the respective output is also on, and if the numerical character is off, the respective output is also off. In case of digital inputs, the numerical characters show the respective logic input state. When the numerical character is on, the respective input is also on, and if the numerical character is off, the respective input is also off. The relationship between the input/output number and its respective numerical character can be found on the following figure.

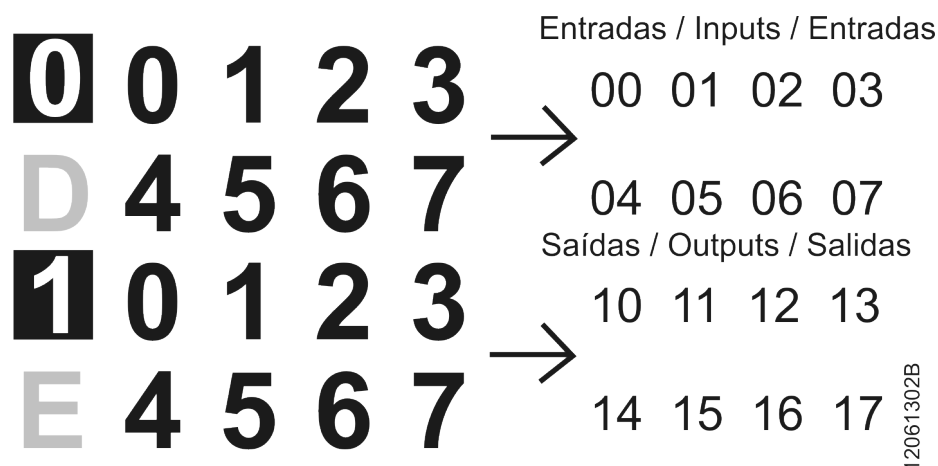


Figure 7: Numerical Character

9.3. Web Page with Complete Status and Diagnostics List

Another way to access diagnostics information on Nexto Series is via web pages. Nexto Series CPU's has an embedded web page server that provides all Nexto status and diagnostics information, which can be accessed using a simple browser.

More information about web page with complete status and diagnostics list can be found at User Manual of each respective CPU (listed at Nexto Series User Manual - MU214600).

9.4. Diagnostics Through Variables

All diagnostics in this module can be accessed through variables that can be handled by the user application or even forwarded to a supervisory system using a communication channel. There are two different ways to access diagnostics in the user application: using symbolic variables with AT directive or addressing memory. Altus recommends use symbolic variables for diagnostic accessing. The table below shows all available diagnostics for this module and their respective memory address, description, symbolic variable and string that will be shown on the CPU graphical display and web.

9.4.1. General Diagnostics

| Direct Represent. | | Diagnostic Message | Symbolic Variable DG_Module.tGeneral.* | Description | PROFIBUS Message Code |
|-------------------|------|--------------------------|---|---|-----------------------------|
| Variable | Bit | | | | |
| %QB(n) | 0..7 | Reserved | | | |
| %QB(n+1) | 0 | MODULE W/ DIAGNOSTICS | bActiveDiagnostics | TRUE – Module has active diagnostics | - |
| | | NO DIAG | | FALSE – Module doesn't have active diagnostic | |
| | 1 | MODULE W/ FATAL ERROR | bFatalError | TRUE – Fatal error | 25 |
| | | - | | FALSE – No fatal error | |
| | 2 | CONFIG. MISMATCH | bConfigMismatch | TRUE – Parameterization error | 26 |
| | | - | | FALSE – Parameterization ok | |
| | 3 | WATCHDOG ERROR | bWatchdogError | TRUE – Watchdog has been detected | 27 |
| | | - | | FALSE – No watchdog | |
| | 4 | OTD SWITCH ERROR | bOTDSwitchError | TRUE – Module has switch failure | 28 |
| | | - | | FALSE – Diagnostics switch ok | |
| | 5..7 | Reserved | | | |

Table 18: General Diagnostics

9.4.2. Detailed Diagnostics

| Direct Represent. | | Diagnostic Message | Symbolic Variable DG_Module.tDetailed.* | Description | PROFIBUS Message Code |
|-------------------|------|-------------------------|--|--|-----------------------------|
| Variable | Bit | | | | |
| %QB(n+2) | 0 | OUTPUT SHORT CIRCUIT | bOutputShortCircuit | TRUE – Short circuit at out- puts 10 to 17 | 16 |
| | | - | | FALSE – No short circuit at outputs 10 to 17 | |
| | 1..7 | Reserved | | | |
| %QB(n+3) | 0 | NO EXTERNAL SUPPLY | bNoExternalSupply | TRUE – No external supply at outputs 10 to 17 | 24 |
| | | - | | FALSE – External supply ok at outputs10 to 17 | |
| | 1..7 | Reserved | | | |

Table 19: Detailed Diagnostics

Notes:

Direct Representation Variable: “n” is the address defined in the field %Q Start Address of Module Diagnostics Area on the NX1005’s configuration screen – Module Parameters tab in the MasterTool IEC XE.

Symbolic Variable: Some symbolic variables serve to access diagnostics. These diagnostics are stored in the direct representation variable, so the AT directive is used to map the symbolic variables in the direct representation variable. The directive AT is a reserved word in the MasterTool IEC XE, that uses this directive to declare the diagnostics automatically on symbolic variables. All symbolic variables declared automatically can be found inside of the Module_Diagnostics object.

9.5. Hot Swap

This product supports hot swap. For further information about how to correctly perform a hot swap, consult Nexto Series User Manual - MU214600.

10. Manuals

For further technical details, configuration, installation and programming, the table below should be consulted.

The table below is only a guide of some relevant documents that can be useful during the use, maintenance, and programming of this product.

| Code | Description | Language |
|-----------------|--|------------|
| CE114000 | Nexto Series – Technical Characteristics | English |
| CT114000 | Série Nexto – Características Técnicas | Portuguese |
| CS114000 | Serie Nexto – Características Técnicas | Spanish |
| MU214600 | Nexto Series User Manual | English |
| MU214000 | Manual de Utilização Série Nexto | Portuguese |
| MU299609 | MasterTool IEC XE User Manual | English |
| MU299048 | Manual de Utilização MasterTool IEC XE | Portuguese |
| MP399609 | MasterTool IEC XE Programming Manual | English |
| MP399048 | Manual de Programação MasterTool IEC XE | Portuguese |
| MU214608 | Nexto PROFIBUS-DP Head Utilization Manual | English |
| MU214108 | Manual de Utilização da Cabeça PROFIBUS-DP Nexto | Portuguese |

Table 20: Related Documents